

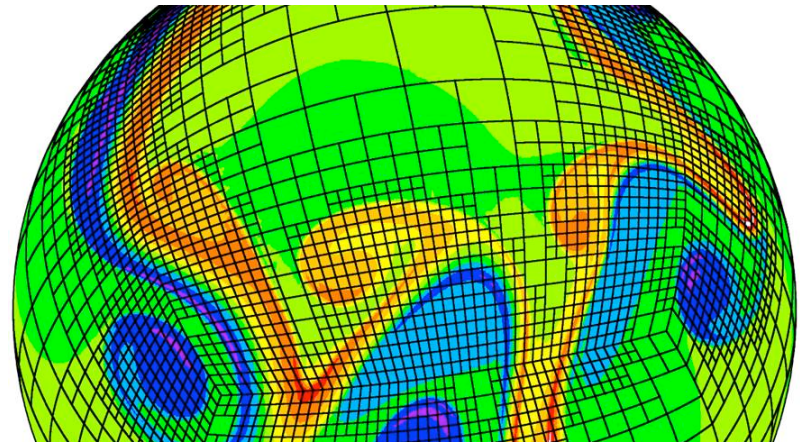
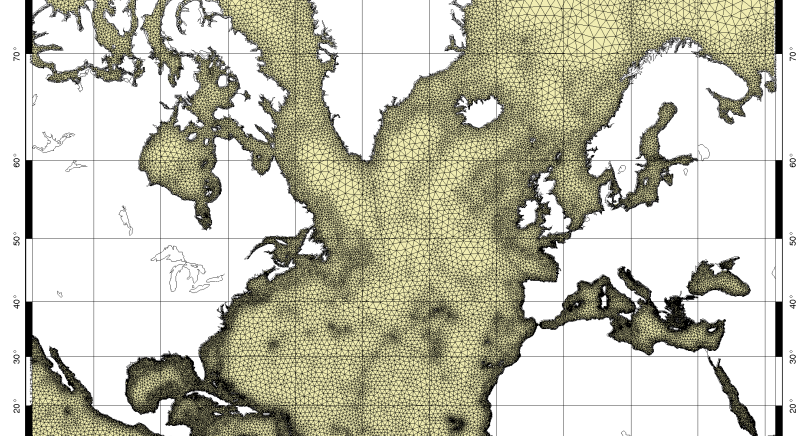
# A comparative performance analysis of oceanic numerical models: numerical and computational aspects

Roland Patoum, Laurent Debreu, Florian Lemarié

Inria and Laboratoire Jean Kuntzmann, Grenoble, France

# Performance of oceanic models

- Numerical schemes
- Computational implementation
- Mesh Refinement



# NEMO CROCO MARS3D - Main characteristics

## ○ NEMO

- Low order time stepping for advection (second order for internal waves)
- Explicit free surface (linear here)
- Use pointers as work arrays
- Array order (l,j,k)
- Masked loops

## ○ CROCO

- High order time stepping for advection (second order for internal waves)
- Non linear explicit free surface
- Smart treatment of work arrays
- Array order (l,j,k)
- Masked loops

## ○ MARS3D

- High order (space-time) time stepping for advection (second order for internal waves)
- Non linear Implicit (ADI) free surface
- Array order (k,l,j)
- Restricted (sea only) loops

# Numerical methods of three oceanic models: stability constraints

Computational performance = efficiency of the time integration schemes

	NEMO	CROCO	MARS3D
Internal Gravity Waves	0.46	0.85	2
External Gravity Waves	0.46	0.9	$\infty$
Advection	0.46	0.87	1

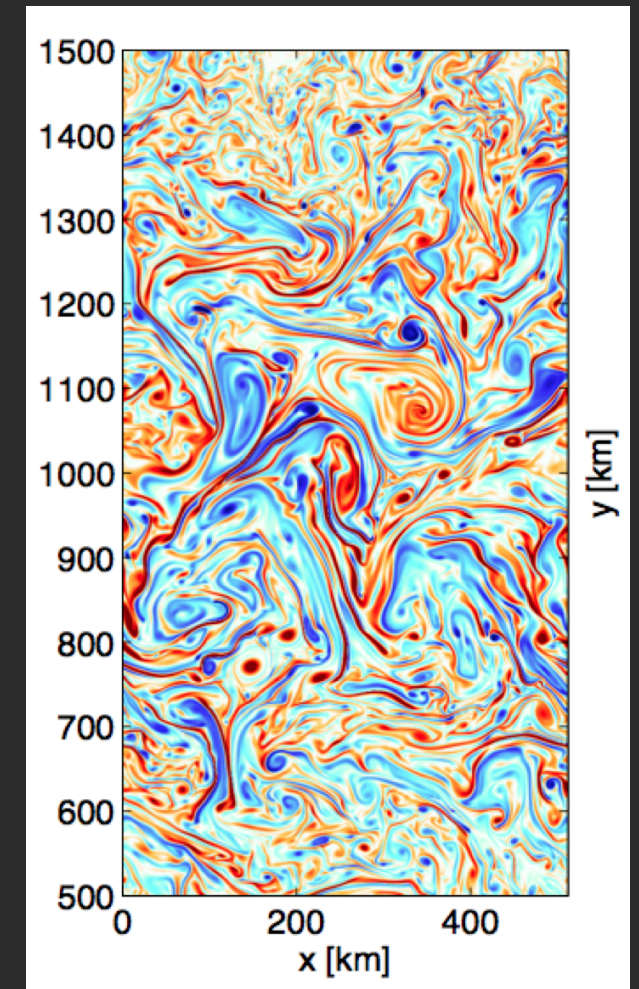
Maximum Courant numbers, Lemarié et al, 2015 (Ocean Modelling)

# A baroclinic test case at 2km (Soufflet et al, OM, 2016) 1000 x 250 x 100 grid points

$$\Delta t \sqrt{(c_1)_{i,j}^2 \left( \frac{1}{(\Delta x_{i,j})^2} + \frac{1}{(\Delta y_{i,j})^2} \right)} \leq \alpha_{igw}^*$$

- Maximum time steps

	NEMO	CROCO	MARS3D
$\Delta t(s)$	200	340	320
$\Delta t_{2D}(s)$	3	6,1	320
$\alpha_{igw}^*$	0.46	0.85	2

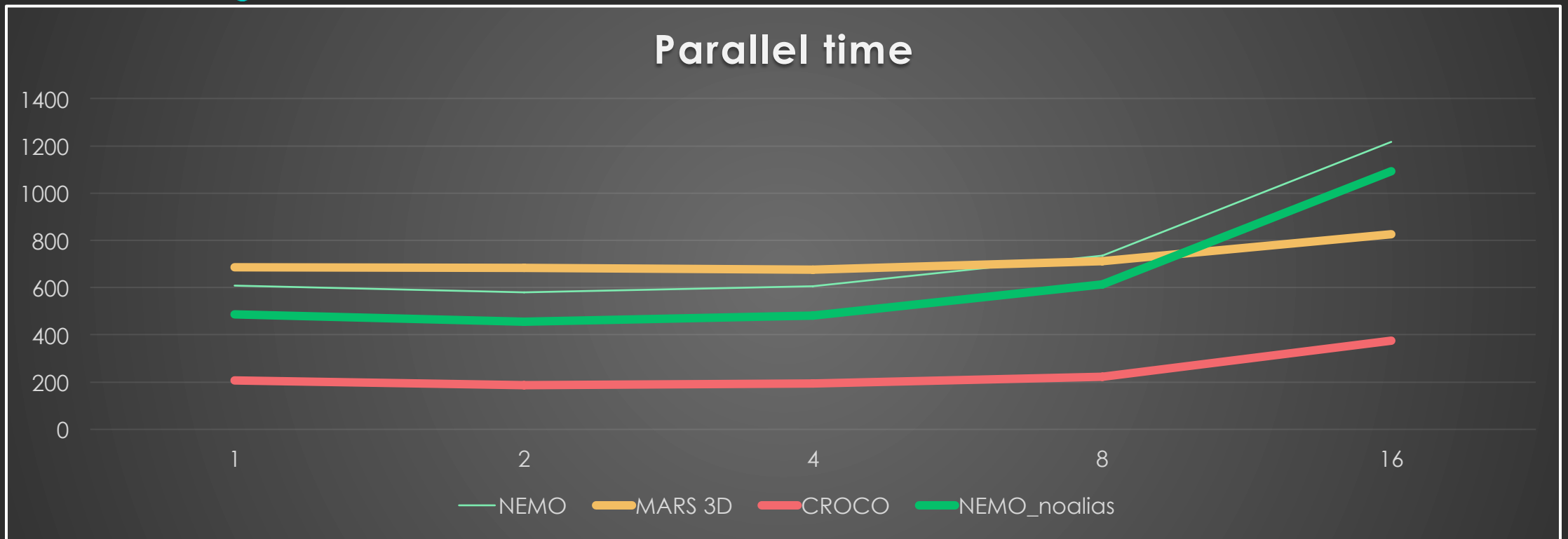


# Sequential performance (Intel VTune)

	NEMO	NEMO (noalias)	CROCO	CROCO (autotiling)	MARS
Memory size	2 Gb	2 Gb	1 Gb	800Mb	1,4 Gb
Number of instructions	5,50 Mds	4,3 Mds	3,2 Mds	3,3 Mds	13,9 Mds
Vectorization (%)	40	65	80	78	45
Cache bound (%)	14	10	13	14	71
DRAM bound (%)	31	36	26	21	15
Execution time (s)	609	486	186	160	686

NEMO uses a linear free surface  
MARS makes a lot of unnecessary tests on water depth  
All codes advect salinity even if not needed ...

# Parallel performance



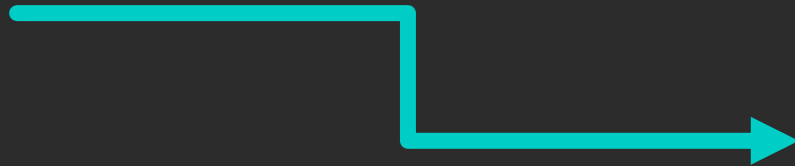
# Analysis

- NEMO
  - Improvement of time integration algorithm is required
  - Management of work arrays
  - Memory size (unnecessary global arrays ?)
- CROCO
  - Improvement of time integration algorithm is possible
- MARS3D
  - Possible instability of momentum advection



# Conclusions

- Improving numerical methods is the easiest way to improve code efficiency
  - (unuseful to try to computationally optimize a code with bad numerics)
  - Need to follow the code evolution
    - Wetting and Drying
    - Non hydrostatic
    - ...



- Increase of resolution
- Incorporate new physics
- Increase of the size of an ensemble

# Other HPC key ingredients

- (Adaptive) mesh refinement
- Online Diagnostics / Visualization
- Hybrid parallelization

